The EL-2650XL is a wireless PIR sensor that is able to distinguish between permitted and non-permitted motion. This allows the occupants free movement within the premises while detecting intrusion via doors or windows. The sensor implements a feature to combat the problem of multiple transmissions, which drastically reduce the life of the batteries. After a transmission is made, the EL-2650XL initiates a delay of approximately four minutes during which transmissions will not be sent. The sensor operates in two selectable modes: Curtain and Directional.

Location of Detector

Consider the following before mounting the sensor:

- Select a location from which the pattern of the sensor is most likely to be crossed by a burglar, should there be a break in.
- Avoid a location that comes in direct contact with radiators, heating/cooling ducts or air conditioners.
- Do not place bulky objects in front of the sensor.

Caution: Do not install the sensor above beds, sofas, desks or in any area that people are likely to spend continued periods of time. If the occupant does not move within the delay time, an alarm will be generated when moving away from the protected area.

Installation Instructions

- To open the housing, remove the cover screw and, using a flathead screwdriver, press
 the locking tab at the side of the unit. Remove the printed circuit board (PCB) by
 unscrewing the PCB screw. Note: Do not touch the face of the PYRO sensor.
- 2. Set the receiver to Registration mode. Apply battery power by removing the isolator that separates the battery from the contacts on the battery holder. The sensor turns on and sends four transmissions in order to be registered with the system. Wait for the receiver to indicate that the transmitter has been registered successfully. Alternatively, the EL-2650XL can be registered to the receiver by manually entering the transmitter's serial number. Note: The receiver allocates a transmitter number to each registered unit. Write this number and the number of the zone on the sticker provided. Affix the sticker inside the front cover for future reference.
- 3. After a warm-up period of 130 sec. indicated by both LEDs' blinking, the sensor automatically enters Radio Mode for 4 minutes approximately and sends transmissions every 8 seconds, then it enters Regular mode see Operation and Adjustment, Selectable Operation Modes.
- Knock out the mounting holes and test the transmitter from the exact mounting position before permanently mounting the unit.
- Attach the base to the wall at the recommended height of 2.2 m. The EL-2650XL can be
 wall or ceiling mounted. Note: The "Alarm" arrow on the PCB (See figures 1 and 2)
 must point inward (i. e. towards the protected area).
- Mount the PCB at the required setting using the horizontal adjustment scale and tighten the PCB screw – see Operation and Adjustment, PCB Adjustment. Attach the front cover and replace the cover screw.

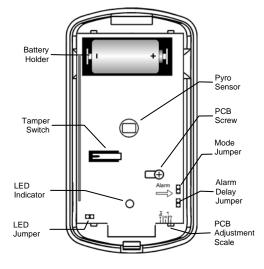


Figure 1: EL-2650XL (Cover Off)

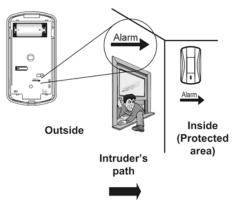
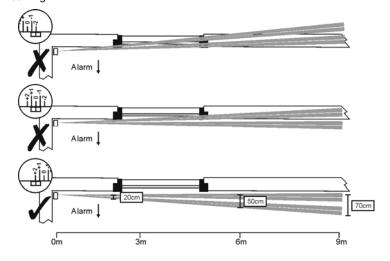


Figure 2: Correct Placement of the Detector

Operation and Adjustment

PCB Adjustment

PCB adjustment enables you to angle the infrared beams by changing the position of the pyro element in relation to the lens. To adjust the PCB, loosen the PCB screw and slide the PCB to the required position using the PCB adjustment scale as a guide. After adjusting the board, tighten the PCB screw. Slide the board towards -2 to position the beams closer to the wall. Slide the board towards +2 to position the beams further away from the wall. For the correct PCB adjustment, you must take into account the distance of the detector from the wall and the distance of the protected door/window from the detector – see Table 1 (below). The settings in Table 1 as illustrated in Figure 3 are relevant both to wall and ceiling mounting.



		Distance of Detector from Wall		
		5cm	25cm	50cm
Distance of Door/Window from Detector	Up to 2m*	+2	0	-1
	4m	+2	0	-1
	6m	+2	0	0
	8m	+2	+1	0
	9m	+2	+1	0

Table 1: Recommended PCB Adjustment Scale Settings for Wall and Ceiling Mounting

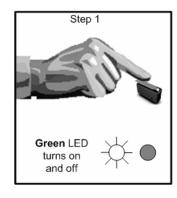
* It is not recommended to mount the unit less than 40cm away from the path of entry protected by the detector.

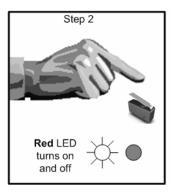
Figure 3: A typical installation where the detector is 5cm from the wall and 2m from the protected window. The top two diagrams show the lens coverage pattern for the detector when incorrectly adjusted to -2 and 0. The bottom diagram shows the PCB correctly adjusted to +2.

Walk Test

A walk test determines the coverage pattern of the detector. To perform this test, walk across the scope of the detector according to the detection pattern selected. Confirm that the LEDs activate and deactivate as described in Table 4. To launch the Walk Test from the *Radio mode*, after any transmission indicated by LED blinking, press the tamper switch and hold it until the green LED turns on then off (see Figure 4, step 1). Release the Tamper switch and wait until the red LED turns on and then off (see Figure 4, step 2). Press the Tamper switch once again. Both LEDS are lit momentarily (see Figure 4, step 3). The sensor enters the Walk Test mode for 4 minutes. During the Walk Test, wait for twenty seconds between movements. To launch the Walk Test from the *Normal mode*: Just open the sensor housing: the tamper is triggered and the sensor enters the Walk Test mode for 4 minutes. Walk test should be performed weekly.

Note: In Walk Test mode there are no delays.





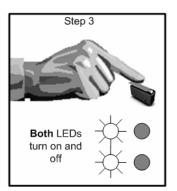


Figure 4: Launching the Walk test from Radio Mode

Selectable Operation Modes

The sensor operates in two operation modes. In Directional Mode, crossing the infrared beams is alarm-protected in one direction only. The protected direction is shown by the arrow printed on the PCB. In case of crossing the beams from the non-permitted side (ALARM), red LED is lit for a second. In case of crossing the beams from the permitted side (NO ALARM), green LED is lit for a second and the Alarm delay (see below) starts to count down. In Curtain mode, crossing the beams is alarm-protected in both directions. The Operation mode (Directional/Curtain) is selected using the Mode Jumper – see Table 2.

Mode Jumper JP3	Jumper Position	
Curtain	Removed	
Directional	Installed	

Table 2

Alarm Delay

The Alarm Delay is a feature designed to allow the occupant to move freely within the protected area without triggering a false alarm. When approaching the protected wall, an alarm is not generated because the sensor's beams are crossed from the permitted direction. After detecting permitted motion, the sensor counts down the Alarm Delay time. This timer is re-triggered every time the sensor detects motion. During the Alarm Delay, the sensor permits motion in both directions. The duration of the alarm delay is selected using the Alarm Delay Jumper – see Table 3.

Delay Jumper JP2	Jumper Position			
1 minute	Removed			
4 minutes	Installed			

Table 3

LED Indication

The LED indicator turns red to indicate non-permitted motion and green to indicate motion detection in either direction. In the event of an alarm, the LED turns red. To disable the LED, remove the LED Jumper, JP1 located next to the LED indicator – see Table 4. Note: Do not disable the LED until you have successfully walk tested the sensor.

PIR Supervision

The circuit operation of the PIR is checked once per hour. In the event of PIR failure the red LED flashes.

LED	Indication
Red	Non-
	permitted
	motion
Green	Permitted
	Motion

Table 4

Technical Specifications

Antenna: Built-in Internal Whip Frequency: 418MHz, 433.92MHz, or 868.35MHz FM Power: 3.6V ½ AA Lithium Battery

Caution: Fire, explosion and severe burn hazard!

Do not recharge, disassemble or heat above 100°C.

Current Consumption: 30mA (transmission), 20µA (standby)

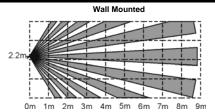
Pyroelectric Sensor: Quad Element

Maximum Range: 9m

Operating Temperature: -20° to 60°C LED indicator: Jumper Selectable

RFI Immunity: 10V/m

Fire Protection: ABS Plastic Housing Dimensions: 90 x 50 x 40mm



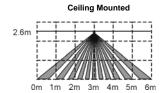


Figure 5: Lens Coverage Pattern (Side View)



Electronics Line 3000 Ltd.: 2 Granit Street, Kiryat Arieh, POB 3253, Petah Tikvah 49130 Israel. Tel: (972-3) 918-1333, Fax: (972-3) 922-0831 USA: 5637 Arapahoe Avenue, Boulder, Colorado 80303. Tel: (800) 683-6835, Fax: (303) 938-8062 UK: Unit 7, Leviss Trading Estate, Station Road, Stechford, Birmingham B33 9AE. Tel: (44-121) 789-8111, Fax: (44-121) 789-8055 SecTecGLOBAL: 156 West 56 Street, Suite 1605, New York, NY 10019, United States, Tel: (1-212) 2652400, Fax: (1-212) 2652419

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